

ABSTRACT

In origin adjustment between two members which rotate relatively at a joint of an industrial robot, an origin adjustment apparatus is provided which is inexpensive and highly accurate
5 and which requires extremely few man hours. In addition, an origin adjustment apparatus is provided which is so small in size as to be easily used even on a distal end shaft of a wrist of the robot and which requires no special signal line for origin
10 adjustment. A mount member 23 where a positioning member 22 is embedded and a guide portion 24 along which the positioning member 22 slides in such a manner as to protrude are provided on either one or both of the two members which rotate relatively.